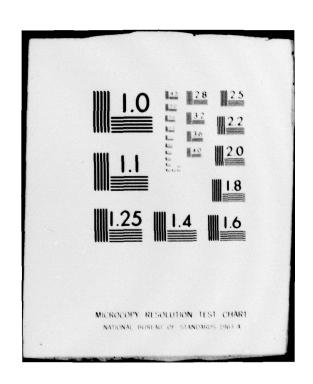
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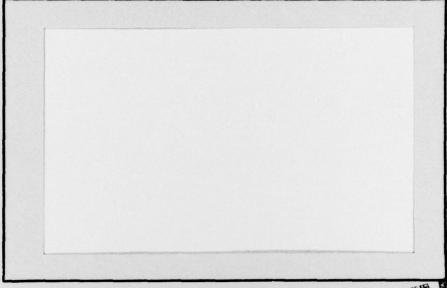
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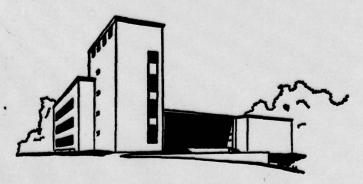
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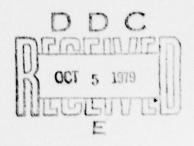
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CONVEX PROGRAMS AND THE IR CLOSURES

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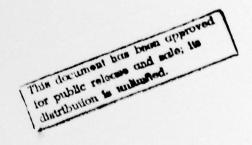
C. E. Blair

J. Borwein²

and

R. G. Jeroslow³

October 1978



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Abstract

We extend the limiting lagrangean equation has elements of the factor of the following the followin

and the results on affine supports from which it was deduced, to a very general setting that subsumes the previous constraint qualifications.

A simple example shows the need for some constraint qualification.

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Key Words:

(1) Nonlinear programming

sup over Lambda

- (2) Lagrangean
- (3) Convexity

CONVEX PROGRAMS AND THEIR CLOSURES

by

C. E. Blair, 1 J. Borwein, 2 and R. G. Jeroslow 3

For a convex function $f: D \to R$ $(D \subseteq R^{\Omega}, D \text{ convex})$ the closure $cl(f): cl(D) \to R \cup \{+\infty\}$ is defined by

(1) $cl(f)(y) = sup\{h(y) | h \text{ linear affine}, h(x) \le f(x) \text{ for all } x \in D\}$ where cl(D) is the closure of the convex set D.

It is well known that: (i) $cl(f)(x) \le f(x)$ for all $x \in D$; (ii) cl(f) is convex; (iii) cl(f)(x) = f(x) for all $x \in relint(D)$, where relint(D) denotes the relative interior of the convex set D.

For a convex optimization problem (with possibly infinitely many constraints)

inf fo(x)

(P)

subject to $f_h(x) \le 0$ for $h \in H$

and x E K

with optimal value denoted v(P), the closure is

 $\inf cl(f_0)(x)$

(P^)

subject to $cl(f_h)(x) \le 0$ for $h \in H$

and x e cl(K)

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with optimal value denoted v(P').

We assume throughout that (P) is consistent.

Duffin [1] and Jeroslow [2] show that when (P) and (P') have the same optimal value, a "limiting Lagrangean" exists, in the sense that (using the homotopy form of the limiting Lagrangean of [2, equation (50)])

(2)
$$\lim_{\theta \to 0+} \sup_{\Lambda} \inf_{\mathbf{x} \in K} \{ f_0(\mathbf{x}) + \theta(\mathbf{w}\mathbf{x} + \mathbf{w}_1) + \sum_{\mathbf{h} \in H} \lambda_{\mathbf{h}} f_{\mathbf{h}}(\mathbf{x}) \} = \mathbf{v}(\mathbf{P})$$

for $w \in \mathbb{R}^n$ and $w_1 \in \mathbb{R}$ suitably chosen, where Λ denotes that space of vectors $(\lambda_h|h\in \mathbb{R})$ which are nonnegative and only finitely non-zero. Moreover, from the value equality v(P) = v(P') also follows "fine detail" from which (2) is deduced, as e.g., [2, Theorem 3] and [2, Corollary 3].

It is also established in [2] that v(P) = v(P') holds in many instances in which the usual constraint qualifications, such as the existence of Slater points, may fail to hold even for |H| finite. This is because the limiting lagrangean (2) is not related to issues of linear affine, or even rather more general, supports to the perturbation function of (P). This aspect of the limiting lagrangean was already present in the first limiting lagrangean, due to R. J. Duffin [1].

The purpose of this note, is to extend the validity of the limiting lagrangean (and Theorem 3 and Corollary 3 of [2]) to a rather broad setting that is associated with the ordinary lagrangean in the case of |H| finite. We show, in this setting, that the limiting lagrangean holds again under weaker hypotheses than the ordinary lagrangean, even for |H| finite; and our result also treats |H| infinite.

Let D_h be the domain of definition of f_h . [2] showed that v(P) = v(P') if relint(K) \leq relint(D_h) for all $h \in \{0\} \cup H$ and there was an $x_0 \in relint(K)$ such that $f_h(x_0) \leq 0$ for all $h \in H$. These latter hypotheses were called (CQ) in [2].

In this note we show:

THEOREM: Let H' denote those indices $h \in \{0\} \cup H$ such that f_h is not closed.

v(P) = v(P') if there is an x_0 satisfying this constraint qualification:

(3) $x_0 \in relint(R) \cap \bigcap_{h \in H} relint(D_h)$ and $f_h(x_0) \le 0$ for $h \in H$. (The intersection over an empty set is defined to be R^n).

<u>PROOF</u>: If x is feasible for (P) it is also feasible for (P') because $cl(f_h)(x) \le f_h(x)$. Since $cl(f_0)(x) \le f_0(x), v(P') \le v(P)$.

To show that $v(P') \ge v(P)$, let x be any feasible point of (P'). For $0 < \lambda < 1$ if $y = \lambda x + (1 - \lambda)x_0$, $y \in K$ and $y \in relint(D_h)$ for all $h \in H'$, by the Accessibility Lemma [5, 3.2.11]. By (iii), $cl(f_h)(y) = f_h(y)$ for all $h \in H'$; therefore $cl(f_h)(y) = f_h(y)$ for all $h \in H \cup \{0\}$.

Since $\operatorname{cl}(f_h)(x_0) \le f_h(x_0) \le 0$ and $\operatorname{cl}(f_h)(x) \le 0$ for $h \in H$, one easily shows (by considering f_h and $\operatorname{cl}(f_h)$ on $[x,x_0]$) that $f_h(y) = \operatorname{cl}(f_h)(y) \le 0$ for $h \in H$. So y is a feasible point for (P).

By semi-continuity $\lim_{\lambda \to 1} cl(f_0)(y) \le cl(f_0)(x)$. But since $cl(f_0)(y) = \lambda + 1$ $f_0(y)$ for all $\lambda < 1$ this implies $v(P) \le cl(f_0)(x)$.

Since x was arbitrary, this shows $v(P) \le v(P^2)$. Hence $v(P) = v(P^2)$, as desired.

<u>REMARK</u>: The same proof shows that, if K is closed, one obtains v(P) = v(P') from:

(4)
$$x_0 \in K \cap \bigcap_{h \in H} relint (D_h)$$
 and $f_h(x_0) \leq 0$ for $h \in H$.

In one of the constraint qualifications of [2], it is assumed that $H' = \phi$ and K is closed, in which case (4) becomes that constraint qualification (CQ)'. Trivially, (4) implies also the constraint qualification (CQ) of [2].

COROLLARY: Suppose that (P) has at least two different feasible points, and that none of the sets K or D_h for $h \in H'$ contains any line segments in K\relint(K) or D_h \relint(D_h) (where H' is as defined in the theorem).

Then
$$v(P) = v(P')$$
.

<u>PROOF</u>: Let $x_a \neq x_b$ both be feasible in (P). Since $x_a, x_b \in K$ and K contains no line segment in K\relint(K), $x_0 = (x_a + x_b)/2 \in relint(K)$. Similarly, $x_0 \in relint(D_h)$ for $h \in H$. Trivially, $f_h(x_0) \le 0$ for $h \in H$.

The result now follows from the theorem.

Q.E.D.

Some constraint qualification is needed to insure that v(P) = v(P'), even for |H| finite. For example, consider this instance of a convex program:

(5)
$$\begin{aligned} &\inf x_1 \\ &\text{subject to} & x_2 \leq 0 \\ &f_2(x_1, x_2) \leq 0 \\ &(x_1, x_2) \in K \end{aligned}$$

where $K = \{(x_1, x_2) | 0 \le x_1 \le 1 \text{ and } x_2 \ge 0\}$ and

(6)
$$f_2(x_1, x_2) = \begin{cases} 0, & 0 \le x_1 \le 1 \text{ and } x_2 > 0; \\ 1 - x_1, & 0 \le x_1 \le 1 \text{ and } x_2 = 0; \\ +\infty, & \text{otherwise.} \end{cases}$$

Here v(P) = 1 and v(P') = 0, since $cl(f_2)(x_1, x_2) \equiv 0$ if $0 \le x_1 \le 1$ and $x_2 \ge 0$. In this example, $H' = \{2\}$, as f_2 is not continuous on line segments that begin in the interior of K and end in the boundary segment $\{(x_1, x_2) | x_2 = 0 \text{ and } 0 \le x_1 \le 1\}$. Here also $x_2 \le 0$ and $(x_1, x_2) \in K$ implies $x_2 = 0$, so $(x_1, x_2) \notin relint(D_2)$; hence (3) fails.

August 2, 1978 Revised September 14, 1978

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